NAG Toolbox for MATLAB

f04ah

1 Purpose

f04ah calculates the accurate solution of a set of real linear equations with multiple right-hand sides, AX = B, with iterative refinement, where A has been factorized by f03af.

2 Syntax

```
[x, bb, k, ifail] = f04ah(a, aa, p, b, eps, 'n', n, 'ir', ir)
```

3 Description

To solve a set of real linear equations AX = B, f04ah must be preceded by a call to f03af which computes an LU factorization of A with partial pivoting, PA = LU, where P is a permutation matrix, L is lower triangular and U is unit upper triangular. An approximation to X is found by forward and backward substitution. The residual matrix R = B - AX is then calculated using **additional precision**, and a correction D to X is found by solving LUD = PR. X is replaced by X + D, and this iterative refinement of the solution is repeated until full machine accuracy has been obtained.

4 References

Wilkinson J H and Reinsch C 1971 Handbook for Automatic Computation II, Linear Algebra Springer-Verlag

5 Parameters

5.1 Compulsory Input Parameters

1: a(lda,n) - double array

lda, the first dimension of the array, must be at least n.

The n by n matrix A.

2: aa(ldaa,n) – double array

ldaa, the first dimension of the array, must be at least n.

Details of the LU factorization, as returned by f03af.

3: p(n) – double array

Details of the row interchanges as returned by f03af.

4: **b(ldb,ir)** – **double** array

ldb, the first dimension of the array, must be at least n.

The n by r right-hand side matrix B.

5: **eps – double scalar**

Must be set to the value of the machine precision.

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5.2 Optional Input Parameters

1: n - int32 scalar

Default: The dimension of the arrays \mathbf{a} , \mathbf{aa} , \mathbf{p} . (An error is raised if these dimensions are not equal.) n, the order of the matrix A.

Constraint: $\mathbf{n} \geq 0$.

2: ir – int32 scalar

Default: The dimension of the arrays \mathbf{b} , \mathbf{x} , \mathbf{bb} . (An error is raised if these dimensions are not equal.)

r, the number of right-hand sides.

5.3 Input Parameters Omitted from the MATLAB Interface

lda, ldaa, ldb, ldx, ldbb

5.4 Output Parameters

1: x(ldx,ir) - double array

The n by r solution matrix X.

2: bb(ldbb,ir) - double array

The final *n* by *r* residual matrix R = B - AX.

3: k - int32 scalar

The number of iterations needed in the refinement process.

4: ifail – int32 scalar

0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

The matrix A is too ill-conditioned to produce a correctly rounded solution.

7 Accuracy

The computed solutions should be correct to full machine accuracy. For a detailed error analysis see page 106 of Wilkinson and Reinsch 1971.

8 Further Comments

The time taken by f04ah is approximately proportional to n^2r .

9 Example

```
a = [33, 16, 72;

-24, -10, -57;

-8, -4, -17];
```

f04ah.2 [NP3663/21]

```
aa = [-8, 0.5, 2.125;
-24, 2, -3;
33, -0.5, 0.375];
p = [3;
       2;
       3];
b = [-359;
       281;
      85];
eps = 1.111307226797642e-16;
[x, bb, k, ifail] = f04ah(a, aa, p, b, eps)
       1
     -2
bb =
       0
       0
       0
k =
ifail =
                0
```

[NP3663/21] f04ah.3 (last)